

- Sub 21
- 1 1. A pipeline inspection system comprising,  
2 a wave launcher in communication with a pipeline and adapted to transmit an  
3 input waveform having a selected input energy along a longitudinal axis of said pipeline,  
4 and to receive a reflected component of said input waveform from said pipeline, said  
5 reflected component having a characteristic reflected energy,  
6 an analyzer in communication with said wave launcher and adapted to generate  
7 said input waveform, and to receive said reflected component of said input waveform  
8 from said wave launcher, and  
9 a processor in communication with said analyzer and adapted to compare said  
10 input waveform with said reflected component of said input waveform to determine a  
11 characteristic of said pipeline.
- 1 2. The apparatus of claim 1, wherein said processor is further adapted to compare  
2 said input waveform with said reflected component to detect an anomaly in said pipeline.
- 1 3. The apparatus of claim 2, wherein said anomaly is at least one of a crack, a  
2 corrosion, a leak, a location of an end wall, an obstruction, a flange, a weld, and a  
3 restriction in said pipeline.
- 1 4. The apparatus of claim 2, wherein said processor is further adapted to compare  
2 said input waveform with said reflected component to determine a location of said  
3 anomaly in said pipeline.
- 1 5. The apparatus of claim 2, wherein said processor is further adapted to compare  
2 said input waveform with said reflected component to determine a shape of said anomaly  
3 in said pipeline.
- 1 6. The apparatus of claim 2, wherein said processor is further adapted to compare  
2 said input waveform with said reflected component to determine one of an absolute size  
3 of said anomaly and a relative size of said anomaly relative to an internal diameter of said  
4 pipeline.
- 1 7. The apparatus of claim 1, wherein said processor is further adapted to compare  
2 said input waveform with said reflected component to determine an axial curvature in  
3 said pipeline.



1 21. The apparatus of claim 20, wherein said input waveform comprises a plurality of  
2 input signals within said range of frequencies.

1 22. The apparatus of claim 21, wherein said analyzer is further adapted to detect  
2 differences in velocity between said plurality of input signals as said input signals  
3 propagate in said pipeline, and said processor is further adapted to determine a curvature  
4 of said pipe along said longitudinal axis from said differences in velocity.

1 23. The apparatus of claim 21, wherein said analyzer is further adapted to detect  
2 differences in velocity between reflected components of each of said plurality of input  
3 signals to determine a curvature of said pipeline along said longitudinal axis.

1 24. The apparatus of claim 1, wherein said analyzer is further adapted to generate an  
2 electromagnetic waveform as said input waveform.

1 25. The apparatus of claim 1, wherein said analyzer is further adapted to generate an  
2 acoustic waveform as said input waveform.

1 26. The apparatus of claim 1, wherein said analyzer is further adapted to generate said  
2 input waveform as one of a spread spectrum waveform, a chirp waveform, and a soliton  
3 waveform.

1 27. The apparatus of claim 1, wherein said analyzer is further adapted to generate said  
2 input waveform as a wideband waveform.

1 28. The apparatus of claim 1 further comprising calibration elements adapted to  
2 temperature stabilize said analyzer.

1 29. A method of inspecting a characteristic of a pipeline, said method comprising,  
2 transmitting an input waveform having a selected input energy along a  
3 longitudinal axis of said pipeline,  
4 receiving a reflected component of said input waveform from said pipeline, said  
5 reflected component having a characteristic reflected energy, and  
6 comparing said input waveform with said reflected component of said input  
7 waveform to determine said characteristic of said pipeline.

1 30. The method of claim 29 further comprising, comparing said input waveform with  
2 said reflected component to detect an anomaly in said pipeline.





5 receiving a reflected component of said input waveform from said pipeline, said  
6 reflected component having a characteristic reflected energy, and  
7 comparing said input waveform with said reflected component of said input  
8 waveform to determine said location of said point along said pipeline.

1 56. A method of inspecting a characteristic of a pipeline, said method comprising,  
2 transmitting an input waveform having a selected input energy along a  
3 longitudinal axis of said pipeline,  
4 receiving a reflected component of said input waveform from said pipeline, said  
5 reflected component having a characteristic reflected energy, and  
6 determining said characteristic of said pipeline using an error estimate, said error  
7 estimate depending on a known point along said pipeline relative to said characteristic.

1 57. The method of claim 56 wherein said error estimate further depends on one of a  
2 conductance, a radius, and a cross-sectional shape of said pipeline.

1 58. A method of inspecting a characteristic of a pipeline, said method comprising,  
2 generating an input waveform,  
3 launching said input waveform into said pipeline,  
4 receiving from said pipeline a reflected component having a characteristic  
5 reflected energy of said input waveform,  
6 calculating a mathematical function of said characteristic reflected energy from  
7 said reflected component of said input waveform,  
8 determining a model mathematical function of model reflected energy from a  
9 model component of a model input waveform, and  
10 determining said characteristic of said pipeline by comparing said mathematical  
11 function of said reflected energy to said model mathematical function of said model  
12 reflected energy.